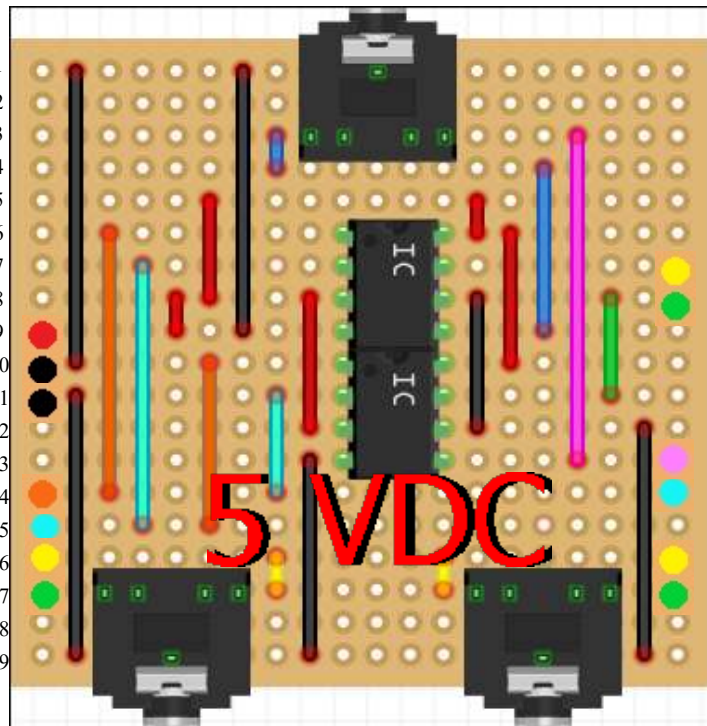


Adaptive RC Sailer Interface PCB (5 VDC) Arduino Shield (20 columns wide x 19 rows high)

Top View

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20



Reset
3.3 V
5 V
GND
GND
Vin
No Pin
A0 Sails Inc
A1 Sails Up/Dwn
A2 Rudder Right
A3 Rudder Left
A4
A5

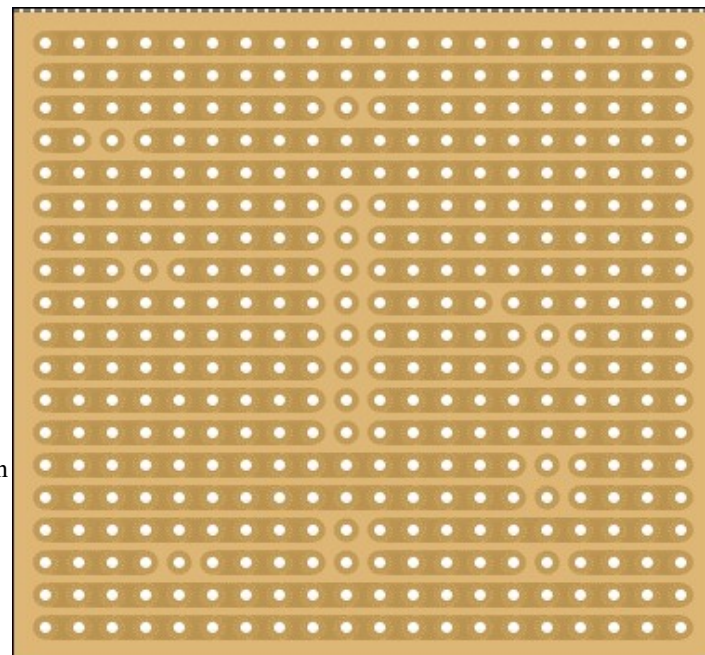
1
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19

1
2
3
4
5
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7
8
9
10
11
12
13
14
15
16
17
18
19

4 GND
5 D13
6 D12
7 D11 Sails CS
8 D10 Rudder CS
9 D9
10 D8
11 No Pin
12 D7
13 D6
14 D5 Rudder Up/Dwn
15 D4 Rudder Inc
16 D3 Sails Out
17 D2 Sails In
18 D1
19 D0

Copper Strip Side with Trace Breaks

20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1



X9C103 Digital Potentiometer Sail & Rudder Pin Assignments

!INC = 1(Inc/Dec) Vcc = 8
U!/D = 2(Up/Dwn) !CS = 7(Chip Select)
Vh/Rh = 3 Vl/Vr = 6
GND = 4 Vw/Rw = 5
Note: Must keep !INC LOW while taking !CS HIGH
U!/D may be changed while !CS is LOW

Arduino Pin Numbers (Not PCB #)

Digital Pins D0 - D13 = Pin # 0 - 13
Analog Pins A0 - A5 = Pin # 14 - 19

X9C Digital Potentiometer #A

X9C_A_Sails__ChipSelectPin7 = D11 (11)
X9C_A_Sails__UpDownPin2 = A1 (15)
X9C_A_Sails__IncDecPin1 = A0 (14)
SailsOutSwitchPin = D3 (3) Ring
SailsInSwitchPin = D2 (2) Tip
X9C #A Pin#5 = Sails Servo (Tip)

Arduino

X9C Digital Potentiometer #B

X9C_B_Rudder__ChipSelectPin7 = D10 (10)
X9C_B_Rudder__UpDownPin2 = D5 (5)
X9C_B_Rudder__IncDecPin1 = D4 (4)
RudderLeftSwitchPin = A3 (17) Ring
RudderRightSwitchPin = A2 (16) Tip
X9C #B Pin#5=Rudder Servo (Ring)

Surrogate Adaptive Switch Simulator

Sails In (Decrement) = Tip Sails Out (Increment) = Ring